# Basic Classification Algorithms 

Rules,

Linear Regression,
Nearest Neighbour

## OUTLINE

- Rules
- Linear Regression
- Nearest Neighbour


## GENERATING RULES

- A decision tree can be converted into a rule set



## Generating Rules

- A decision tree can be converted into a rule set


$$
A>5 \quad \& \& \quad B>=0 \quad \& \& \quad A>=9 \quad->\quad-
$$

## GENERATING RULES

- A decision tree can be converted into a rule set


$$
\begin{array}{lllllll}
A>5 & \& \& & B>=0 & \& \& & A>=9 & -> & - \\
A>5 & \& \& & B>=0 & \& \& & A<9 & -> & +
\end{array}
$$

## GENERATING RULES

- A decision tree can be converted into a rule set


| $A>5$ | $\& \&$ | $B>=0$ | $\& \&$ | $A>=9$ | $->$ | - |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $A>5$ | $\& \&$ | $B>=0$ | $\& \&$ | $A<9$ | $->$ | + |
| $A>5$ | $\& \&$ | $B<0$ | $\& \&$ | $B<7$ | $->$ | + |

## GENERATING RULES

- A decision tree can be converted into a rule set


| $\mathrm{A}>5$ | $\& \&$ | $\mathrm{~B}>=0$ | $\& \&$ | $\mathrm{~A}>=9$ | $->$ | - |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathrm{A}>5$ | $\& \&$ | $\mathrm{~B}>=0$ | $\& \&$ | $\mathrm{~A}<9$ | $->$ | + |
| $\mathrm{A}>5$ | $\& \&$ | $\mathrm{~B}<0$ | $\& \&$ | $\mathrm{~B}<7$ | $->$ | + |
| $\mathrm{A}>5$ | $\& \&$ | $\mathrm{~B}<0$ | $\& \&$ | $\mathrm{~B}>=7$ | $->$ | - |

## GENERATING RULES

- A decision tree can be converted into a rule set


| $A>5$ | $\& \&$ | $B>=0$ | $\& \&$ | $A>=9$ | $->$ | - |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $A>5$ | $\& \&$ | $B>=0$ | $\& \&$ | $A<9$ | $->$ | + |
| $A>5$ | $\& \&$ | $B<0$ | $\& \&$ | $B<7$ | $->$ | + |
| $A>5$ | $\& \&$ | $B<0$ | $\& \&$ | $B>=7$ | $->$ | - |
| $A<=5$ | $->$ | + |  |  |  |  |

## Generating Rules

- A decision tree can be converted into a rule set


| $\mathrm{A}>5$ | $\& \&$ | $\mathrm{~B}>=0$ | $\& \&$ | $\mathrm{~A}>=9$ | $->$ | - |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathrm{A}>5$ | $\& \&$ | $\mathrm{~B}>=0$ | $\& \&$ | $\mathrm{~A}<9$ | $->$ | + |
| $\mathrm{A}>5$ | $\& \&$ | $\mathrm{~B}<0$ | $\& \&$ | $\mathrm{~B}<7$ | $->$ | + |
| $\mathrm{A}>5$ | $\& \&$ | $\mathrm{~B}<0$ | $\& \&$ | $\mathrm{~B}>=7$ | $->$ | - |
| $\mathrm{A}<=5$ | $->$ | + |  |  |  |  |

- Often overly complex, simplifying is not trivial
- tests each node in root-leaf path to see if it can be eliminated without loss in accuracy (C4.5rule)


## COVERING ALGORITHMS

- Generate rule sets directly
- for each class:
- find rule set that covers all instances in it (excluding instances of other classes)
- Covering approach
- at each stage a rule is identified that covers some of the instances



## EXAMPLE:

## GENERATING A RULE

Class a


IF TRUE then class $=a$

## EXAMPLE:

## GENERATING A RULE

Class a


IF $\mathrm{X}>1.2$ then class $=\mathrm{a}$

## EXAMPLE:

## GENERATING A RULE

Class a


IF $X>1.2$ and $Y>2.6$ then class $=a$

## EXAMPLE:

## GENERATING A RULE

Class b, rule 1


IF $\mathrm{X} \leq 1.2$ then class $=\mathrm{b}$

## EXAMPLE:

## GENERATING A RULE

Class b, rule 2


IF $\mathrm{X}>1.2$ and $\mathrm{Y} \leq 2.6$ then class $=\mathrm{b}$

## EXAMPLE:

## GENERATING A RULE

Class b, rule 2


IF $\mathrm{X}>1.2$ and $\mathrm{Y} \leq 2.6$ then class $=\mathrm{b}$

- More rules could be added for a "perfect" rule set


## EXAMPLE:

## GENERATING A RULE



IF $\mathrm{X} \leq 1.2$ then class $=\mathrm{b}$
ELSE IF $\mathrm{X}>1.2$ and $\mathrm{Y} \leq 2.6$ then class $=\mathrm{b}$
ELSE class = a

## RULES => TREES



IF $\mathrm{X} \leq 1.2$ then class $=\mathrm{b}$
ELSE IF $\mathrm{X}>1.2$ and $\mathrm{Y} \leq 2.6$ then class $=\mathrm{b}$ ELSE class $=\mathbf{a}$


## RULES VS. Trees

## Rules (PRISM)

IF $\mathrm{X} \leq 1.2$ then class $=\mathrm{b}$
ELSE IF $\mathrm{X}>1.2$ and $\mathrm{Y} \leq 2.6$ then class $=\mathrm{b}$
ELSE class $=\mathrm{a}$


## Trees (C4.5)



Overall, rules generate clearer subsets, especially when decision trees suffer from replicated subtrees

## A Simple covering ALgorithm (PRISM)

- Generate a rule by adding tests that maximize rule's accuracy
- Goal: maximize accuracy $p / t$
- $t$ : total number of instances covered by rule
- $\quad$ : ‘positive' examples of the class covered by rule
- $t-p$ : number of errors made by rule
- Stop when $p / t=1$ or the set of instances can't be split any further (can't test twice on same attribute)


## PRISM

## PsEUDO-CODE

For each class C
Initialize D to the instance set
While D contains instances in class $C$
Create a rule R with an empty left-hand side that predicts class C
Until $R$ is perfect (or there are no more attributes to use) do
For each attribute A not mentioned in R, and each value v,
Consider adding the condition $\mathrm{A}=\mathrm{v}$ to the left-hand side of R
Select A and v to maximize the accuracy $\mathrm{p} / \mathrm{t}$
(break ties by choosing the condition with the largest p )
Add $\mathrm{A}=\mathrm{v}$ to R
Remove the instances covered by R from D

## CONTACT LENS DATA

| age | spectacle-prescrip | astigmatism | tear-prod-rate | contact-lenses |
| :---: | :---: | :---: | :---: | :---: |
| young | myope | no | reduced | none |
| young | myope | no | normal | soft |
| young | myope | yes | reduced | none |
| young | myope | yes | normal | hard |
| young | hypermetrope | no | reduced | none |
| young | hypermetrope | no | normal | soft |
| young | hypermetrope | yes | reduced | none |
| young | hypermetrope | yes | normal | hard |
| pre-presbyopic | myope | no | reduced | none |
| pre-presbyopic | myope | no | normal | soft |
| pre-presbyopic | myope | yes | reduced | none |
| pre-presbyopic | myope | yes | normal | hard |
| pre-presbyopic | hypermetrope | no | reduced | none |
| pre-presbyopic | hypermetrope | no | normal | soft |
| pre-presbyopic | hypermetrope | yes | reduced | none |
| pre-presbyopic | hypermetrope | yes | normal | none |
| presbyopic | myope | no | reduced | none |
| presbyopic | myope | no | normal | none |
| presbyopic | myope | yes | reduced | none |
| presbyopic | myope | yes | normal | hard |
| presbyopic | hypermetrope | no | reduced | none |
| presbyopic | hypermetrope | no | normal | soft |
| presbyopic | hypermetrope | yes | reduced | none |
| presbyopic | hypermetrope | yes | normal | none |

## Rule: IF true, Then hard <br> Next step?

| age | spectacle-prescrip | astigmatism | tear-prod-rate | contact-lenses |
| :---: | :---: | :---: | :---: | :---: |
| young | myope | no | reduced | none |
| young | myope | no | normal | soft |
| young | myope | yes | reduced | none |
| young | myope | yes | normal | hard |
| young | hypermetrope | no | reduced | none |
| young | hypermetrope | no | normal | soft |
| young | hypermetrope | yes | reduced | none |
| young | hypermetrope | yes | normal | hard |
| pre-presbyopic | myope | no | reduced | none |
| pre-presbyopic | myope | no | normal | soft |
| pre-presbyopic | myope | yes | reduced | none |
| pre-presbyopic | myope | yes | normal | hard |
| pre-presbyopic | hypermetrope | no | reduced | none |
| pre-presbyopic | hypermetrope | no | normal | soft |
| pre-presbyopic | hypermetrope | yes | reduced | none |
| pre-presbyopic | hypermetrope | yes | normal | none |
| presbyopic | myope | no | reduced | none |
| presbyopic | myope | no | normal | none |
| presbyopic | myope | yes | reduced | none |
| presbyopic | myope | yes | normal | hard |
| presbyopic | hypermetrope | no | reduced | none |
| presbyopic | hypermetrope | no | normal | soft |
| presbyopic | hypermetrope | yes | reduced | none |
| presbyopic | hypermetrope | yes | normal | none |

## EXAMPLE: CONTACT LENS DATA

- Rule we seek to refine:


## If ?

then recommendation $=$ hard

- Possible tests:

| Age = Young | $2 / 8$ |
| :--- | :--- |
| Age = Pre-presbyopic | $1 / 8$ |
| Age = Presbyopic | $1 / 8$ |
| Spectacle prescription = Myope | $3 / 12$ |
| Spectacle prescription = Hypermetrope | $1 / 12$ |
| Astigmatism = no | $0 / 12$ |
| Astigmatism = yes | $4 / 12$ |
| Tear production rate = Reduced | $0 / 12$ |
| Tear production rate = Normal | $4 / 12$ |

## EXAMPLE: CONTACT LENS DATA

- Rule we seek to refine:

$$
\begin{aligned}
& \text { If ? } \\
& \text { then recommendation }=\text { hard }
\end{aligned}
$$

- Possible tests:

```
Age \(=\) Young\(2 / 8\)
```

Age = Pre-presbyopic ..... 1/8
Age $=$ Presbyopic ..... 1/8
Spectacle prescription $=$ Myope ..... $3 / 12$
Spectacle prescription $=$ Hypermetrope ..... $1 / 12$
Astigmatism = no ..... $0 / 12$
Astigmatism = yes ..... $4 / 12$
Tear production rate $=$ Reduced ..... $0 / 12$

## Rule: IF astigmatism=yes, Then hard

| Age | Spectacle prescription | Astigmatism | Tear production rate | Recommended lenses |
| :--- | :--- | :--- | :--- | :--- |
| Young | Myope | Yes | Reduced | None |
| Young | Myope | Yes | Normal | Hard |
| Young | Hypermetrope | Yes | Reduced | None |
| Young | Hypermetrope | Yes | Normal | Hard |
| Pre-presbyopic | Myope | Yes | Reduced | None |
| Pre-presbyopic | Myope | Yes | Normal | Hard |
| Pre-presbyopic | Hypermetrope | Yes | Reduced | None |
| Pre-presbyopic | Hypermetrope | Yes | Normal | None |
| Presbyopic | Myope | Yes | Reduced | None |
| Presbyopic | Myope | Yes | Normal | Hard |
| Presbyopic | Hypermetrope | Yes | Reduced | None |
| Presbyopic | Hypermetrope | Yes | Normal | None |

## Next step?

## FURTHER REFINEMENT

- Current state:

```
If astigmatism = yes
    and?
    then recommendation = hard
```

- Possible tests:

```
Age = Young 2/4
Age = Pre-presbyopic 1/4
Age = Presbyopic 1/4
Spectacle prescription = Myope 3/6
Spectacle prescription = Hypermetrope 1/6
Tear production rate = Reduced 0/6
Tear production rate = Normal 4/6
```


## FURTHER REFINEMENT

- Current state:

```
If astigmatism = yes
    and ?
    then recommendation = hard
```

- Possible tests:

```
Age = Young 2/4
Age = Pre-presbyopic 1/4
Age = Presbyopic 1/4
Spectacle prescription = Myope 3/6
Spectacle prescription = Hypermetrope 1/6
Tear production rate = Reduced 0/6
Tear production rate = Normal

\section*{IF astigmatism=yes \(\mathcal{E}\) tear_production_rate=normal, Then hard}
\begin{tabular}{|l|l|l|l|l|}
\hline Age & Spectacle prescription & Astigmatism & Tear production rate & Recommended lenses \\
\hline Young & Myope & Yes & Normal & Hard \\
\hline Young & Hypermetrope & Yes & Normal & hard \\
\hline Pre-presbyopic & Myope & Yes & Normal & Hard \\
\hline Pre-presbyopic & Hypermetrope & Yes & Normal & None \\
\hline Presbyopic & Myope & Yes & Normal & Hard \\
\hline Presbyopic & Hypermetrope & Yes & Normal & None \\
\hline
\end{tabular}

Next step?

\section*{FURTHER REFINEMENT}
- Current state:

If astigmatism = yes
and tear production rate \(=\) normal and ?
then recommendation \(=\) hard
- Possible tests:
\[
\begin{array}{ll}
\text { Age = Young } & 2 / 2 \\
\text { Age = Pre-presbyopic } & 1 / 2 \\
\text { Age = Presbyopic } & 1 / 2 \\
\text { Spectacle prescription }=\text { Myope } & 3 / 3 \\
\text { Spectacle prescription }=\text { Hypermetrope } & 1 / 3
\end{array}
\]
- Tie between the first and the fourth test
- We choose the one with greater coverage

\section*{FURTHER REFINEMENT}
- Current state:

If astigmatism \(=\) yes
and tear production rate \(=\) normal and ?
then recommendation \(=\) hard
- Possible tests:
\begin{tabular}{ll} 
Age \(=\) Young & \(2 / 2\) \\
Age \(=\) Pre-presbyopic & \(1 / 2\) \\
Age = Presbyopic & \(1 / 2\) \\
Spectacle prescription \(=\) Myope & \(3 / 3\) \\
Spectacle prescription \(=\) Hypermetrope & \(1 / 3\)
\end{tabular}
- Tie between the first and the fourth test
- We choose the one with greater coverage

\section*{IF astigmatism=yes \(\mathcal{E}\) tear_production_rate \(=\) normal \(\mathcal{E}\) spectacle_prescription=myope, Then hard}
\begin{tabular}{|l|l|l|l|l|}
\hline Age & Spectacle prescription & Astigmatism & Tear production rate & Recommended lenses \\
\hline Young & Myope & Yes & Normal & Hard \\
\hline Pre-presbyopic & Myope & Yes & Normal & Hard \\
\hline Presbyopic & Myope & Yes & Normal & Hard \\
\hline
\end{tabular}

Next step?

\section*{The result}
- Final rule:

If astigmatism \(=\) yes and tear production rate \(=\) normal and spectacle prescription = myope then recommendation \(=\) hard
- Second rule for recommending "hard lenses": (built from instances not covered by first rule)

If age = young and astigmatism = yes
and tear production rate \(=\) normal
then recommendation \(=\) hard
- These two rules cover all "hard lenses":
- Process is repeated with other two classes

\section*{RULES VS. DECISION LISTS}
- PRISM with outer loop removed generates a decision list for one class
- Subsequent rules are designed for rules that are not covered by previous rules
- Order doesn't matter: all rules predict the same class
- Outer loop considers all classes separately: no class order
- Order-independent rules are problematic:
- Example has multiple classifications (overlapping rules)
- Choose rule with highest coverage
- Example has no classification at all (default rule)
- Default class

\section*{RULES VS. Decision Trees}
- Methods like PRISM (dealing with one class) are separate-and-conquer algorithms:
- First, a rule is identified
- Then, all instances covered by the rule are separated out
- Finally, the remaining instances are "conquered"
- Others, like Decision Trees, are divide-and-conquer methods:
- First, data is split
- Then, each split modeled / conquered independently

\section*{OUTLiNE}
- Rules
- Linear Regression
- Nearest Neighbor

\section*{LINEAR MODELS}
- Work most naturally with numeric attributes
- Basic technique for numeric prediction: linear regression
- Outcome is linear combination of attributes
\[
x=w_{0}+w_{1} a_{1}+w_{2} a_{2}+\ldots+w_{k} a_{k}
\]
- Weights are calculated from the training data
- Predicted value for first training instance \(\mathbf{a}^{(1)}\)
\[
\begin{aligned}
& x^{(1)}=w_{0} a_{0}^{(1)}+w_{1} a_{1}^{(1)}+w_{2} a_{2}^{(1)}+\ldots+w_{k} a_{k}^{(1)}=\sum_{j=0}^{k} w_{j} a_{j}^{(1)} \\
& \mathrm{a}_{0}=1 \text { (added for convenience) }
\end{aligned}
\]

\section*{LINEAR REGRESSION}
\[
x=w_{0}+w_{1} a_{1}+w_{2} a_{2}+\ldots+w_{k} a_{k}
\]


\section*{LINEAR REGRESSION}

It doesn't always fit

\section*{LINEAR REGRESSION}

It doesn't always fit





\section*{Minimizing THE SQUARED ERROR}
\(x=w_{0}+w_{1} a_{1}+w_{2} a_{2}+\ldots+w_{k} a_{k}\)
- Choose \(k+1\) coefficients (weights) to minimize the squared error on the training data:
\[
\text { squared error }=\sum_{i=1}^{n}\left(x^{(i)}-\sum_{j=0}^{k} w_{j} a_{j}^{(i)}\right)^{2}
\]
- Derive coefficients using standard matrix operations
- Accurate method if enough data available
- Minimizing the absolute error is more difficult

\section*{StANDARD MATRIX OPERATIONS? (EXTRA)}
- Residuals: \(\epsilon=\mathbf{X}\) - Aw
\[
\sum \epsilon_{i}^{2}=\left[\epsilon_{1} \epsilon_{2} \cdots \epsilon_{n}\right]\left[\begin{array}{c}
\epsilon_{1} \\
\epsilon_{2} \\
\vdots \\
\epsilon_{n}
\end{array}\right]=\epsilon^{\prime} \epsilon
\]
- Minimize \(\epsilon^{\prime} \epsilon=(\mathbf{X}-\mathbf{A w})^{\prime}(\mathbf{X}-\mathbf{A w}) \square\)
- Derivative: \(d / d w\left((X-A w)^{\prime}(X-A w)\right)=-2 A^{\prime}(X-A w)^{\prime}\)
- Minimal for: \(-2 \mathbf{A}^{\prime}(\mathbf{X}-\mathrm{Aw})^{\prime}=\mathbf{0}\)
- Thus: \(\mathbf{A}^{\prime} \mathbf{X}=\mathbf{A}^{\prime} \mathbf{A w}\)
- Solve: \(w=\left(\mathbf{A}^{\prime} \mathbf{A}\right)^{-1} \mathbf{A}^{\prime} \mathbf{X}\)

\section*{MANY OTHER (BETTER) WAYS...}

Simple linear regression

\section*{REGRESSION FOR CLASSIFICATION}
- Any regression technique can be used for classification
- Similar to a membership function
- Training:
- Perform a regression for each class, setting the output to 1 for training instances that belong to class, and 0 for others
- Prediction:
- Predict class corresponding to model with largest output value
- For linear regression this is known as multi-response linear regression

\section*{LOGISTIC REGRESSION}
- Problem:
- model output is not a proper probability (can be \(>1\) )
- least squares assumes that errors are statistical independent and normally distributed (wrong: only 0's and 1's)

Linear regression


Logistic regression


\section*{LOGISTIC REGRESSION}
- Logistic regression: alternative to linear regression
- Designed for classification problems
- Transform \(\{0,1\}\) values to [-inf, +inf], build model, transform to [0,1]
- Similar to `odds’
- \(\mathrm{P}(\mathrm{y}=1)=0.75->\mathrm{P} /(1-\mathrm{P})=3->1\) is \(3 x\) more likely than 0
- Replace target variable \(\mathrm{P}[1\) | \(\mathrm{w} 0, \mathrm{w} 1, \ldots \mathrm{wk}]\) by logit transform
\[
\begin{gathered}
\log \left(\frac{P}{1-P}\right)=w_{0} a_{0}+w_{1} a_{1}+w_{2} a_{2}+\ldots+w_{k} a_{k} \\
P=\text { Class probability }=\mathrm{P}[1 \mid \mathrm{w} 0, \mathrm{~W} 1, \ldots \mathrm{Wk}]
\end{gathered}
\]
- Choose \(\mathbf{w}\) to maximize log-likelihood (not so simple)
- maximum likelihood method

\section*{LOGISTIC REGRESSION}
- Resulting model:

- Classification: class with highest probability

\section*{LINEAR MODELS \\ FINAL THOUGHTS}
- Not appropriate if data exhibits non-linear dependencies
- But: can serve as building blocks for more complex schemes (i.e. model trees: trees with models in the leaves)
- Example: multi-response linear regression defines a hyperplane for any two given classes
- Given two weight vectors for two classes, predict class 1 when:
\[
\begin{aligned}
& w_{0}^{(1)} a_{0}+w_{1}^{(1)} a_{1}+w_{2}^{(1)} a_{2}+\ldots+w_{k}^{(1)} a_{k}>w_{0}^{(2)} a_{0}+w_{1}^{(2)} a_{1}+w_{2}^{(2)} a_{2}+\ldots+w_{k}^{(2)} a_{k} \\
& \left(w_{0}^{(1)}-w_{0}^{(2)}\right) a_{0}+\left(w_{1}^{(1)}-w_{1}^{(2)}\right) a_{1}+\left(w_{2}^{(1)}-w_{2}^{(2)}\right) a_{2}+\ldots+\left(w_{k}^{(1)}-w_{k}^{(2)}\right) a_{k}>0
\end{aligned}
\]

\section*{LINEAR MODELS \\ FINAL THOUGHTS}
- Linear classifiers have limitations, e.g. can't learn XOR
- But: combinations of them can ( \(\rightarrow\) Neural Nets)
- Perceptron (1-layer neural network): adjust weights to move hyperplane towards misclassified examples by adding/subtracting the example

\section*{Exclusive Or problem}



\section*{OUTLINE}
- Rules
- Linear Regression
- Nearest Neighbor

\section*{INSTANCE-BASED REPRESENTATION}
- Simplest form of learning: rote learning
- Don't build a model, 'remember' the training instances
- Training instances are searched for instance that most closely resembles new instance
- The instances themselves represent the knowledge
- Also called instance-based learning, or lazy learning
- Similarity function defines which instances are ‘similar'
- Methods:
- nearest-neighbor
- \(k\)-nearest-neighbor

\section*{1-NN EXAMPLE}

\section*{1-Nearest Neighbour}


\section*{THE DISTANCE FUNCTION}
- One numeric attribute
- Distance \(=\) difference between the two attribute values involved (or a function thereof)
- Several numeric attribute
- e.g. Euclidean distance is used and attributes are normalized
- Nominal attributes:
- Distance \(=1\) if values are different, 0 if they are equal
- Are all attributes equally important?
- Usually not, weighting the attributes might be necessary

\section*{EUCLIDEAN DISTANCE}
- Most instance-based schemes use Euclidean distance:
\[
\sqrt{\left(a_{1}^{(1)}-a_{1}^{(2)}\right)^{2}+\left(a_{2}^{(1)}-a_{2}^{(2)}\right)^{2}+\ldots+\left(a_{k}^{(1)}-a_{k}^{(2)}\right)^{2}}
\]
\(\mathbf{a}^{(1)}\) and \(\mathbf{a}^{(2)}\) : two instances with \(k\) attributes
- Taking the square root is not required when comparing distances
- Other popular metric: city-block (Manhattan) metric
- Adds differences without squaring them

\section*{NORMALIZATION}
- Different attributes are measured on different scales \(\Rightarrow\) need to be normalized:
\[
a_{i}=\frac{v_{i}-\min v_{i}}{\max v_{i}-\min v_{i}} \text { or } a_{i}=\frac{v_{i}-\operatorname{Avg}\left(v_{i}\right)}{\operatorname{StDev}\left(v_{i}\right)}
\]
\(v_{i}\) : the actual value of attribute \(i\)
- Nominal attributes: distance either 0 or 1
- Common policy for missing values: assumed to be maximally distant (given normalized attributes)

\section*{K-NN EXAMPLE}

\section*{k-Nearest Neighbour}

- k-NN approach: majority vote (or other function) to derive label
- \(\mathrm{k}=\) regularization parameter: higher k means smoother decision boundary, less overfitting

\section*{Nearest Neighbors}
- Very accurate (for few attributes, lots of data)
- Curse of dimensionality: Every added dimension increases distances, exponentially more training data needed
- Typically very slow (at prediction time):
- simple versions scan all training data to make prediction
- better training set representations exist: kD-tree, ball tree,...
- Assumes all attributes are equally important
- Remedy: attribute selection or weighted distance measures
- Noisy data:
- Take a majority vote over the \(k\) nearest neighbors
- Removing noisy instances from dataset (difficult!)
- Statisticians have used \(k\)-NN since early 1950s
- If \(n \rightarrow \infty\) and \(k / n \rightarrow 0\), error approaches minimum```

